

LIMIT CONTROLLER



NOVA PD570 Series

Instruction Manual

PD570 & PD578

PRECISION DIGITAL CORPORATION



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Nova PD570 Series Model Number Guide

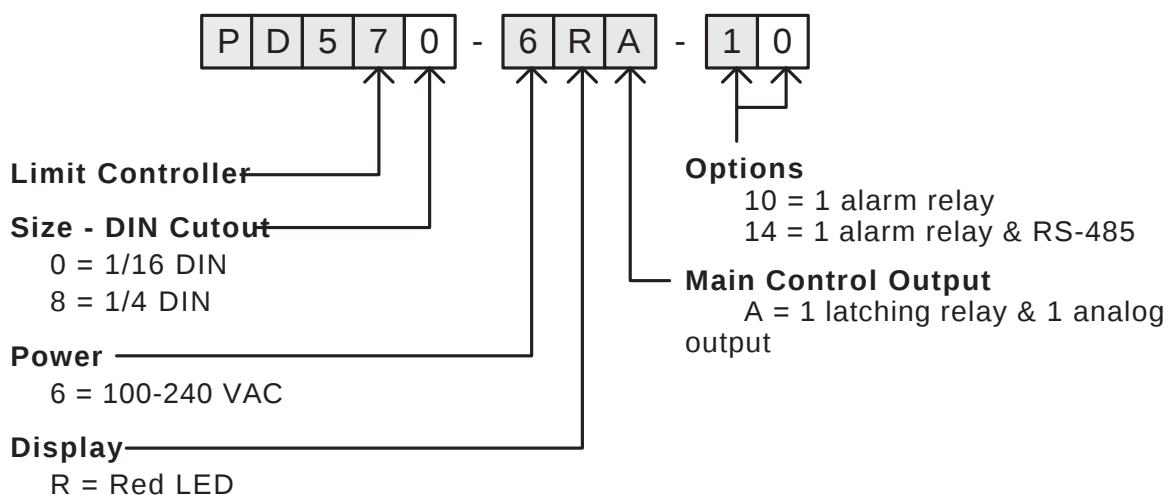


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1. Safety Guide and Specifications



The following safety symbols are used in this manual

- (1) This symbol notifies the user of specific information relating to the safe operation of the controller. Information noted with this symbol must be observed to protect the user from injury and to prevent damage to the product.
 - (A) For User: Be aware of this marking in the manual and refer to the explanation in the manual to prevent injury and damage.
 - (2) For Installer: Study the warnings marked to prevent injury and damage.



- (2) Functional earth terminal: This symbol indicates that the terminal must be connected to ground.



- (3) This symbol indicates additional information on the features of the product.



- (4) This symbol directs the reader to further information on the current topic.



Precautions Regarding This Instruction Manual

- (1) This manual must be kept in the possession of the end user and in a suitable place for the operator to study and to check the functions of the product.
- (2) The installer and operator should carefully study and understand how to operate this product before use.
- (3) This manual describes the functions of the product. Precision Digital Corporation does not guarantee that the functions will suit a particular purpose.
- (4) The contents of this manual have been reviewed for accuracy and correctness. However, should any errors or omissions come to the attention of the user, contact technical support as listed on the back of this manual



Safety Procedures and Unauthorized Modification Warning

- (1) In order to protect this product and the system controlled by it against damage and ensure its safe use, make certain that all of the safety instructions and precautions in this manual are strictly adhered to.
- (2) Precision Digital Corporation does not guarantee safety if the products are not handled in accordance with this instruction manual.
- (3) If separate protection or safety circuits are to be installed in the system which is controlled by this product, ensure that such circuits are installed external to this product.
- (4) Do not make modifications or additions internally to the product. It may cause personal injury to the user or damage to the product.
- (5) Contact technical support as listed on the back of the manual for warranty and repair issues.
- (6) Exposure to excessive moisture, electrical overloads, or mechanical vibration may damage the product.



Limited Liability

Precision Digital Corporation assumes no liability to any party for any loss or damage, direct or indirect, caused by the use of or any unpredictable defect of the product.



Operational Environment Precautions

- (1) Only operate the controller when it is properly installed.
- (2) When installing the controller, select a location where:
 - Rear terminals are protected from accidental contact.
 - Mechanical vibrations are minimal.
 - No corrosive gas is present.
 - Temperature fluctuation is minimal.
 - Temperature can be maintained between 10 and 50 °C (50 and 110°F) with 20 to 90% RH.
 - No direct heat radiation is present.
 - High levels of electromagnetic interference are not present
 - The unit is not exposed to water.
 - No flammable materials are present.
 - Dust particles are not present in the air.
 - Exposure to ultraviolet rays is minimal.
 - Openings on the rear of the controller are not blocked.
- (3) This unit is suitable for installation in an environment classified as Pollution Degree 2.
- (4) This unit is designated as Installation Category II.
- (5) If the equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.
- (6) A switch or circuit-breaker acting as the disconnect device shall be included in the application or the installation.



Controller Mounting Precautions

- Keep the input circuit wiring as far as possible away from power and ground circuits.
- Keep the units in 10 to 50°C (50 to 110°F) with 20% to 90% relative humidity (RH).
The controller may need a warm up period to return to operating temperature ranges when below 10°C.
- To prevent electric shock, be sure to turn off the power source and circuit breaker before wiring.
- The power requirements are 100 to 240 VAC, 50/60 Hz, 10 VA max. Do not switch power supplies without first disconnecting the power supply.
- Follow the operating procedures and precautions in the manual to avoid fire, shock, damage to the unit, or injury. Follow the operations and mounting directions indicated in this manual.
- Always create a ground connection where indicated, however do not ground to gas pipes, water pipes, lightning rods, or other potentially hazardous metal objects.
- Do not apply power to the unit until all connections have been made.
- Do not cover the venting holes in the rear of the unit.

1.1 SPECIFICATIONS

Except where noted all specifications apply to operation at 23°C.

General

DISPLAY	Dual 4 digits, red LED, -1999 to 9999			
	DIN Sizes	PV Display mm (inch)	SP Display mm (inch)	Weight g (oz)
	1/16	11.3 (0.45)	9.5 (0.37)	198 (7.0)
	1/4	20.5 (0.81)	11.0 (0.43)	389 (13.7)
FRONT PANEL	1/16 DIN: IP65; 1/4 DIN: IP55			
SAMPLING TIME	250 ms			
OVERRANGE	Over range PV reads $\overline{0000}$, under range PV reads $-\overline{0000}$			
PROGRAMMING METHODS	Four front panel buttons and Modbus			
NOISE FILTER	Programmable from 1 to 120			
CALIBRATION	All ranges are calibrated at the factory			
MAX/MIN DISPLAY	Max/min readings reached by the process are stored until limit reset or until power to the controller is turned off.			
OVER LIMIT TIMER	Time since the last PV over limit occurrence is stored until the system is reset by the user or until power to the controller is turned off.			
PASSWORD	Programmable password restricts modification of programmed settings			
POWER	100-240 VAC, 50/60 HZ, 10 Watts			
FUSE	Required fuse: UL Recognized, 1 A, 250 V, slow blow			
ISOLATION	2300 V input-to-output-to-power line; 4 kV relay output-to-input/output/power line			
ENVIRONMENTAL	Operating temperature range: 10°C to 50°C (50°F to 110°F) Relative humidity: 20 to 90% non-condensing			
MOUNTING	1/16 or 1/4 DIN size cutout required Two panel mounting bracket assemblies provided for PD578 One one-piece bracket provided for the PD570			
WARRANTY	Three years parts and labor			

Process and Temperature Inputs

TEMPERATURE DRIFT	Refer to accuracy specifications below
DECIMAL POINT	Up to three decimal places for process inputs: 9.999, 99.99, 999.9, or 9999
REAR JUNCTION COMPENSATION	Automatic or off settings for temperature inputs. No user calibration required.
OFFSET ADJUSTMENT	Four programmable input bias zones
SENSOR BREAK DETECTION	Open sensor indicated by PV display flashing 5.0Pn . Up or down scale, user selectable; relays will follow the up or down scale selection.
TRANSMITTER SUPPLY	14 to 18 VDC @ 20 mA; available at terminals OUT2 or OUT3, instead of a retransmitting analog output

UNIVERSAL INPUT TYPE AND ACCURACY

		Temp Range (°C)	Temp Range (°F)	Accuracy*
Input Type	K1	-200 to 1370	-300 to 2500	> 0°C : ±0.1% FS ±1 digit < 0°C : ±0.2% FS ±1 digit
	K2	-199.9 to 999.9	0 to 2300	
	J	-199.9 to 999.9	-300 to 2300	
	T	-199.9 to 400.0	-300 to 750	
	B	0 to 1800	32 to 3300	> 400°C : ±0.15% FS ±1 digit < 400°C : ±5% FS ±1 digit
	R	0 to 1700	32 to 3100	
	S	0 to 1700	32 to 3100	±0.15% FS ±1 digit
	E	-199.9 to 999.9	-300 to 1800	> 0°C : ±0.1% FS ±1 digit < 0°C : ±0.2% FS ±1 digit
	L	-199.9 to 900.0	-300 to 1600	
	U	-199.9 to 400.0	-300 to 750	
RTD	N	-200 to 1300	-300 to 2400	> 0°C : ±0.1% FS ±1 digit < 0°C : ±0.25% FS ±1 digit
	W	0 to 2300	32 to 4200	
	Platinel II	0 to 1390	32 to 2500	±0.1% FS ±1 digit
	PtA	-199.9 to 850.0	-300 to 1560	±0.1% FS ±1 digit**
	PtB	-199.9 to 500.0	-199.9 to 999.9	
Process	PtC	-19.99 to 99.99	-4.0 to 212.0	±0.2% FS ±1 digit
	JPtA	-199.9 to 500.0	-199.9 to 999.9	±0.1% FS ±1 digit**
	JPtB	-150.0 to 150.0	-199.9 to 300.0	
Process	0.4 to 2.0 V	0.400 to 2.000		±0.1% FS ±1 digit Display range can be scaled between -1999 and 9999. 4 to 20 mA Input To accept a 4 to 20 mA signal, select 0.4 to 2.0 VDC input and connect a 100 Ω resistor across the input terminals.
	1 to 5 V	1.000 to 5.000		
	0 to 10 V	0.00 to 10.00		
	-10 to 20 mV	-10.00 to 20.00		
	0 to 100 mV	0.0 to 100.0		

*Performance within recommended operating conditions (10 to 50°C, 20 to 90% RH)

**For a range scale of 0 to 100°C: +0.3°C +1 digit, and for a range scale of -100 to 100°C: +0.5°C +1 digit

Relay Outputs

RATINGS	Out1: 250 VAC @ 3 A or 30 VDC @ 3 A (resistive load) Alarm: 250 VAC @ 1 A or 30 VDC @ 1 A (resistive load)
ELECTRICAL NOISE SUPPRESSION	A suppressor (snubber) should be connected to each relay contact switching inductive loads, to prevent disruption to the microprocessor's operation. Recommended suppressor value: 0.1 μ F/470 Ω , 250 VAC (PDX6901)
DEADBAND	For alarm operations, 0-100% of full scale, user selectable
HIGH OR LOW ALARM	User may program the alarm relay for high or low trip point
DEVIATION ALARM	User may program the alarm relay for a high, low, or range set point deviation alarm.
RELAY OPERATION	Out 1, the Limit Control Relay, will activate when the PV exceeds the limit set point. It will remain in this state until the PV no longer exceeds the limit set point and the relay is reset by the user. The alarm relay may be set to any alarm type.
TIME DELAY	0 to 99 minutes 59 seconds alarm trip delay for each alarm.
FAIL-SAFE OPERATION	Programmable Independent for each alarm relay
AUTO INITIALIZATION	When power is applied to the controller, alarm relays will reflect the state of the input to the controller except standby alarms.

Retransmitting Output

OUTPUT RANGE	Retransmitting: 4 to 20 mA (600 Ω maximum)
SCALING RANGE	Any display range (see range for the input selected)
ACCURACY	$\pm 0.1\%$ of full scale

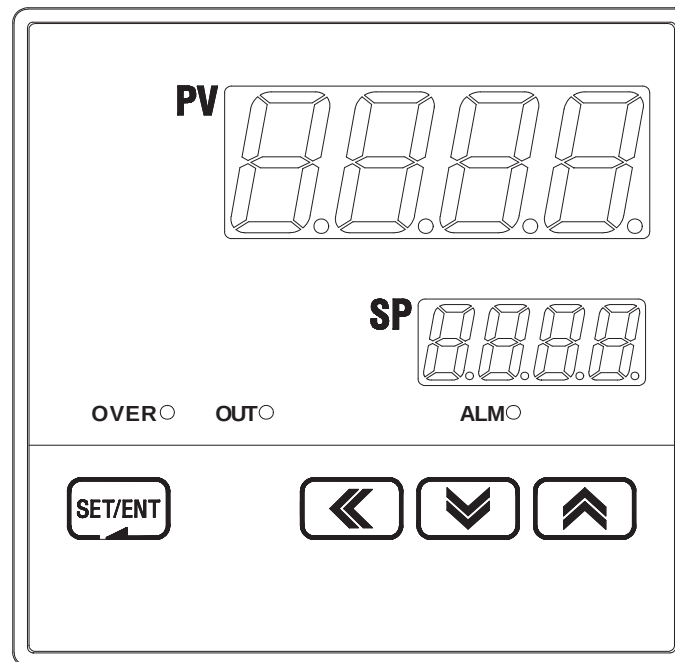
Serial Communications

PROTOCOLS	Modbus (ASCII, RTU), PC software,
UNIT ADDRESS	1 to 99 (Max 31 units connected)
BAUD RATE	600, 1200, 2400, 4800, 9600, 19200 bps, user selectable
RESPONSE TIME	0 to 100 ms delay response time 10 ms increments user selectable
DATA	7 or 8 bit user selectable
PARITY	None, even, or odd

Approvals

UL RECOGNIZED	USA and Canada Process Control Equipment
UL FILE NUMBER	E244207
CE COMPLIANT	

2. Front Panel Buttons and LED Indicators



Control Keys

KEY	Function
SET/ENT (ENTER)	Pressing SET/ENT key for at least 3 seconds switches between the operating display and the parameter setting display. This key is used to verify and bypass parameter settings when in the parameter group display.
▲ / ▼ (UP/DOWN)	Used to change the value of digits when setting parameters. Used to move between parameter groups.
◀ (SHIFT)	Used to move to the next digit when setting parameters.
◀ RST	Holding for 3 seconds will reset the limit control latching relay if it is not in an over limit condition. This will reset the time, maximum, and minimum display values.

LED Display

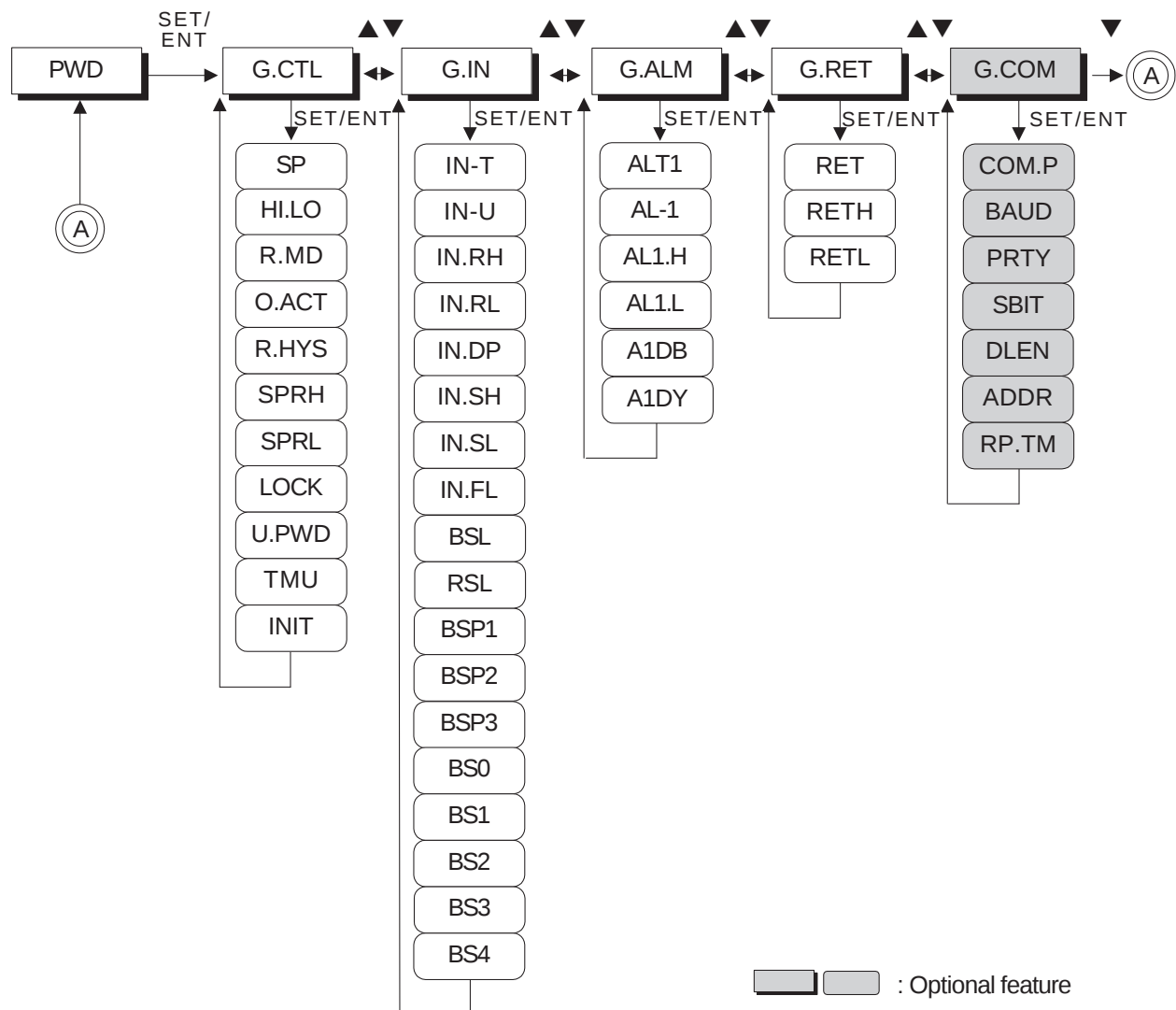
LED	Function
OVER	LED activated when the PV value is higher than the limit setting if HI.LO is set to HI.
OUT	LED activated when the PV value is lower than the limit setting if HI.LO is set to LOW. LED on while the latching relay is de-energized (when in over limit conditions for reverse/failsafe mode).
ALM	LED on when the alarm relay energizes.

3. Parameter Map

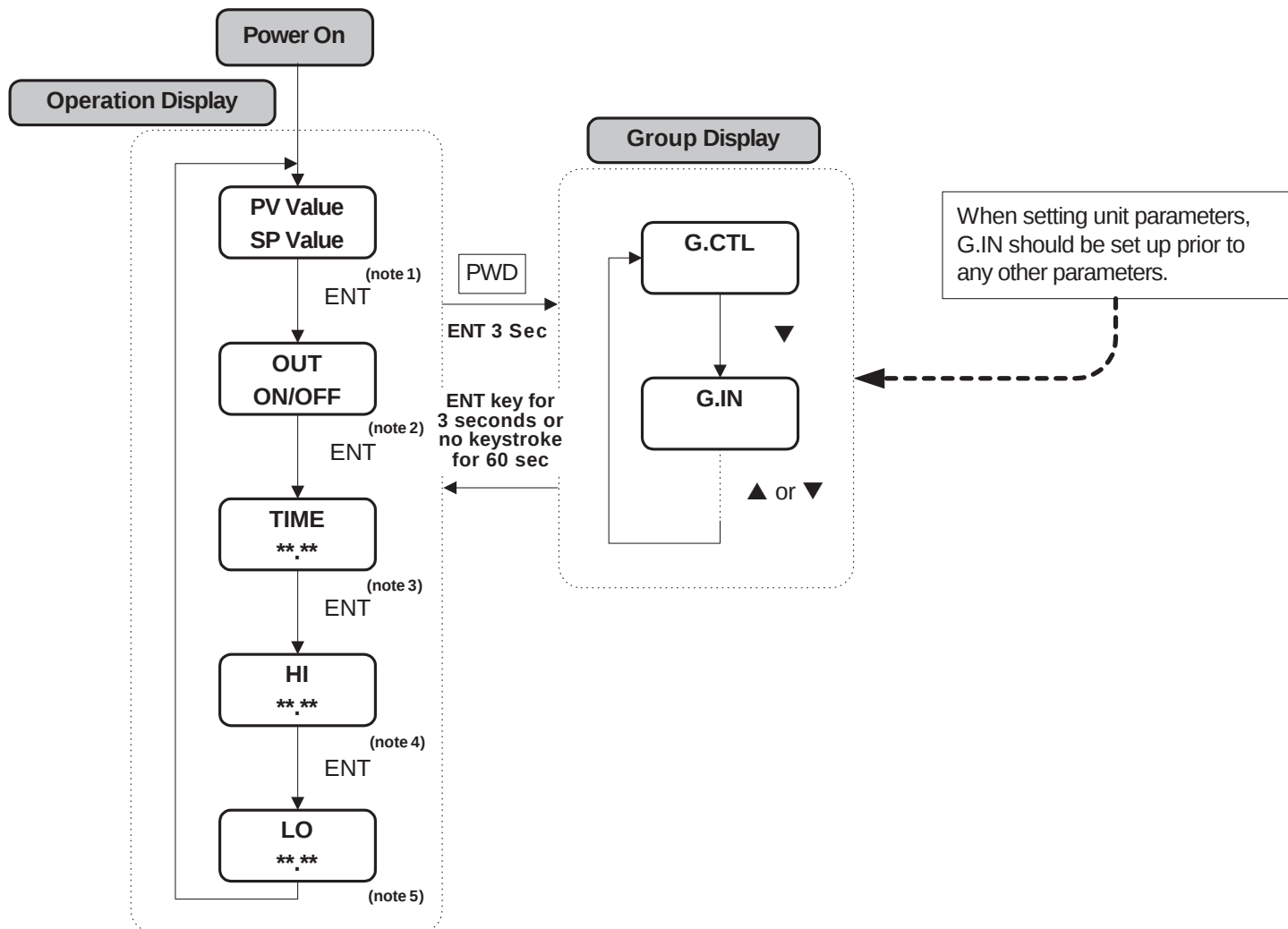


Pwd: Lockout Password

Use the ▲▼ arrows to enter the password and press the SET/ENT key. The default password is 0.



4. Operation Flow Chart



note 1: Initial display at startup.

note 2: Output status for the latching relay.

note 3: The time that has passed since the PV last went over limit.

note 4: Highest PV value. Used only when HI.LO parameter is set to HIGH.

note 5: Lowest PV. Used only when HI.LO parameter is set to Low.

5. Controller Parameter Setup

5.1 Input Group (G.IN)

PV G. In

Press SET/ENT key to select input group. Press press ▲ or ▼ key to cycle through groups as shown below. (Refer to parameter map in section 3.)



Input group parameters should be established first, as changes to the input type may reset other parameter settings in other groups to their default value.

PV In-t

This parameter selects the type of input sensor used. Its default setting is type TC.K1. Refer to the following table showing the type of sensor inputs and select the desired input type.

Table 1: Universal Input Selection

display range : -5% to 105%

No.	TYPE	Temp.Range(°C)	Temp.Range(°F)	Group	DISP	
1	K1	-200 to 1370	-300 to 2500	Thermocouple	ECX1	
2	K2	-199.9 to 999.9	0 to 2300		ECX2	
3	J	-199.9 to 999.9	-300 to 2300		ECJ	
4	E	-199.9 to 999.9	-300 to 1800		ECE	
5	T	-199.9 to 400.0	-300 to 750		ECT	
6	R	0 to 1700	32 to 3100		ECr	
7	B	0 to 1800	32 to 3300		ECb	
8	S	0 to 1700	32 to 3100		ECs	
9	L	-199.9 to 900.0	-300 to 1600		ECI	
10	N	-200 to 1300	-300 to 2400		ECn	
11	U	-199.9 to 400.0	-300 to 750		ECU	
12	W	0 to 2300	32 to 4200		ECy	
13	Platinel II	0 to1390	32 to 2500		ECPL	
14	PtA	-199.9 to 850.0	-300 to 1560	RTD (0.00385)	PtA	
15	PtB	-199.9 to 500.0	-199.9 to 999.9		PtB	
16	PtC	-19.99 to 99.99	-4.0 to 212.0		PtC	
17	JPtA	-199.9 to 500.0	-199.9 to 999.9	RTD (0.00392)	JPtA	
18	JPtB	-150.0 to 150.0	-199.9 to 300.0		JPtB	
19	0.4 to 2.0V	0.400 to 2.000V		VDC	2V	
20	1 to 5V	1.000 to 5.000V			5V	
21	0 to 10V	0.00 to 10.00V			10V	
22	-10 to 20mV	-10.00 to 20.00mV		mVDC	20mV	
23	0 to 100mV	0.0 to 100.0mV			100mV	



4-20 mA Input Selection:

To accept a 4-20 mA signal, select 0.4 to 2.0 VDC input and connect a 100 Ω resistor across the input terminals.

	This parameter sets the display temperature unit for °C or °F. Its default selection is °C. Refer to Table 1 when changing the temperature unit for the temperature input range.
	This parameter sets the high limit of the temperature display range (maximum temperature displayed). For mV and V inputs, this sets the value of the high input of the input scale defined in In.SH.
	This parameter sets the low limit of the temperature display range (minimum temperature displayed). For mV and V inputs, this sets the low input of the input scale defined in In.SL.
	This parameter sets the position of the decimal point for mV or V inputs. The position of the decimal point can be set as 9999, 999.9, 99.99, or 9.999. Its default set value is 1.
	This parameter sets the high limit of the mV or V display scale. This value will be displayed when the input is set to the high input established in In.rH. Its default value is 100.0.
	This parameter sets the low limit of the mV or V display scale. This value will be displayed when the input is set to the low input established in In.rL. Its default value is 0.0.
	This parameter sets the PV filter for stabilization from electromagnetic noise and interference. This will effect the rate of change of the PV display value. Its default setting is OFF, and can be set from 1 to 120 seconds.
	This parameter to establishes PV behavior when an open input sensor is detected. When BSL is set to UP, the PV operates as if at the high input range. When BSL is set to DOWN, the PV operates as if at the low input range. Its default setting is UP. In the case of mV or V inputs, the default setting is OFF. An open sensor check is not performed in 10 V, 20 mV, or 100 mV input settings.
	This parameter determines if RJC for thermocouple inputs is used. RJC can be turned on or off. Its default setting is ON.
 ⋮ 	This parameter sets where the PV bias points occur. See Fig 1 and Fig 2 for further information about input bias operation.
 ⋮ 	This parameter sets the bias value at the corresponding bias point input values. These parameters establish the value of the offset at each of the defined BSP1 - BSP3 points. See Fig 1 and Fig 2 for further information about input bias operation.

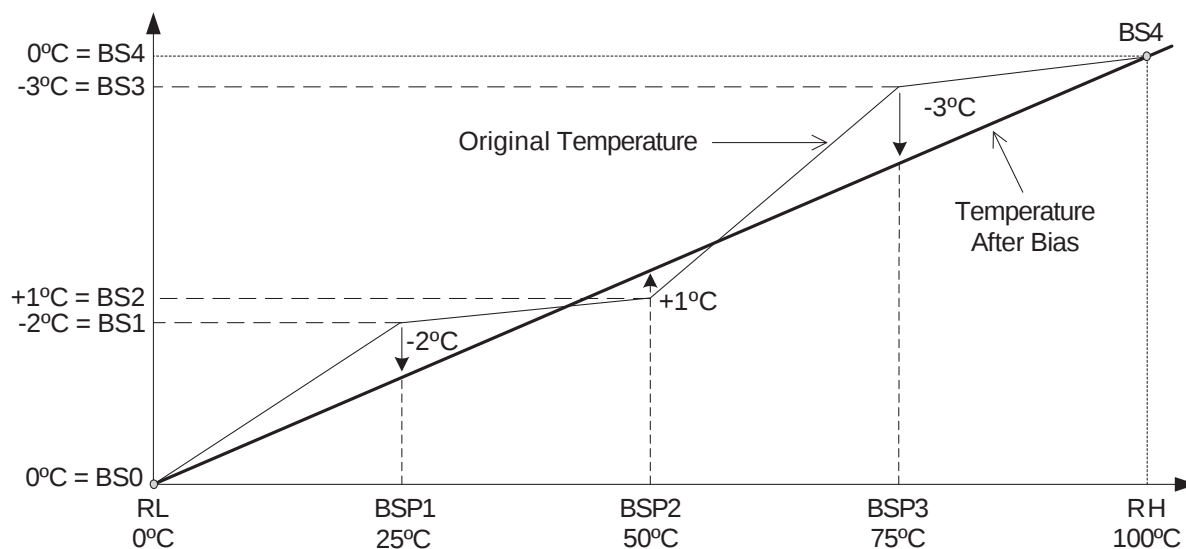


Fig 1: Temperature Bias

Example 1: The original temperature is shown within the range of 0°C (Range Low) and 100°C (Range High). Bias points have been used to adjust the displayed temperature as shown in the graph in Fig 1.

To establish this bias, the settings are shown below.

Temperature Settings to Establish Where the Bias Occurs				
RL	BSP1	BSP2	BSP3	RH
0°C	25°C	50°C	75°C	100°C
Bias Offset for Each Point				
BS0	BS1	BS2	BS3	BS4
0°C	-2°C	+1°C	-3°C	0°C

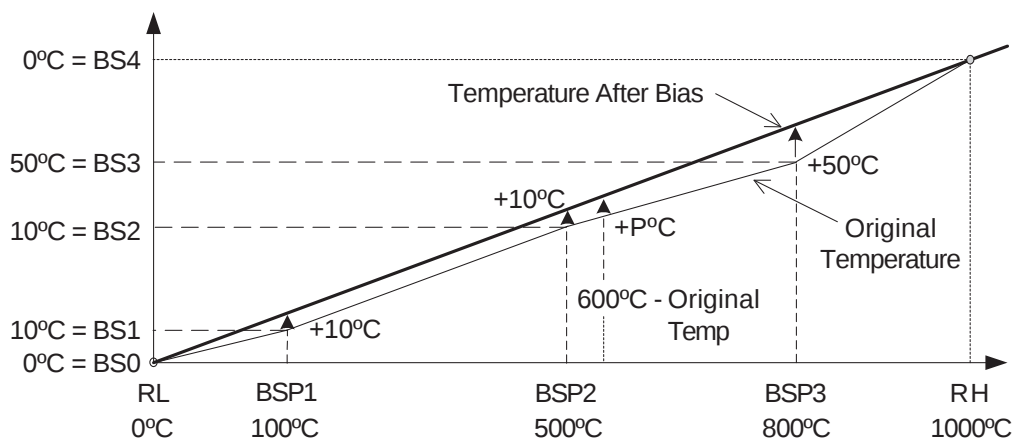


Fig 2: Bias Formula Calculation

Example 2: Temperature Bias Value (BS0 through BS4) = Temperature After Bias - Actual Temperature
Display temperature after bias at 600°C actual temperature = P

$$P = 600 + (600 - \text{BSP2}) \times \frac{\text{BS3} - \text{BS2}}{\text{BSP3} - \text{BSP2}} + \text{BS2}$$

$$P = 600 + (600 - 500) \times \frac{50 - 10}{800 - 500} + 10 = 623^\circ\text{C Temperature After Bias}$$

Input Group Parameter Summary

Display	Parameter	Setting Range	Unit	Default	Remark
IN-T	Input Type	Refer to Table 1: Universal Input Selection	ABS	TC.K1	
IN-U	Display Unit	°C / °F	ABS	°C	T/C, RTD
IN.RH	Max PV Display Range	Within sensor input range Refer to Table 1 INRH > INRL	AEU	1370	
IN.RL	Min PV Display Range		AEU	-200	
IN.DP	Decimal Point Position	0, 1, 2, or 3	ABS	1	mV, V
IN.SH	Max Input Value Scale	-1999 to 9999 INSH > INSL Decimal position determined by IN.DP	ABS	100.0	mV, V
IN.SL	Min Input Value Scale			0.0	mV, V
IN.FL	PV Filter	OFF, 1 to 120	sec	OFF	
BSL	Open Sensor Behavior	OFF, UP, DOWN	ABS	UP	Not Used for VDC input
RSL	RJC Operation	ON, OFF	ABS	ON	Only Used for TC Input
BSP1	Reference Bias Point 1	AEU (0.0 to 100.0%), RL≤BSP1≤BSP2≤BSP3≤RH	AEU	AEU (100.0%)	
BSP2	Reference Bias Point 2	AEU (0.0 to 100.0%), RL≤BSP1≤BSP2≤BSP3≤RH	AEU	AEU (100.0%)	
BSP3	Reference Bias Point 3	AEU (0.0 to 100.0%), RL≤BSP1≤BSP2≤BSP3≤RH	AEU	AEU (100.0%)	
BS0	Bias Value for RL Point	GEU (-100.0 to 100.0%)	GEU	0	
BS1	Bias Value at BSP1	GEU (-100.0 to 100.0%)	GEU	0	
BS2	Bias Value at BSP2	GEU (-100.0 to 100.0%)	GEU	0	
BS3	Bias Value at BSP3	GEU (-100.0 to 100.0%)	GEU	0	
BS4	Bias Value at RH	GEU (-100.0 to 100.0%)	GEU	0	

**NOTE**

There are two types of engineering units values used in the setting of parameters, absolute engineering units (AEU) and general engineering units (GEU). An AEU parameter is set using an absolute value engineering unit that represents a specific point, such as a specific temperature or voltage level. An GEU parameter is set using engineering units, however it is a general value, and not tied to any input or output level.

For example: When establishing input bias, parameter BSP1 sets the specific PV value where bias point one will occur. This parameter has a unit designation of AEU. BS1, the amount of offset at BSP1 is set in engineering units, however this parameter occurs at whatever BSP1 is set to, and therefore does not have an absolute setting related to any input or output, it is just the amount of offset at where BSP1 occurs. While one is related to an absolute input value, and the other stand alone value, both are set as engineering units, such as BSP1 set as 100°C and BS1 set as 3°C.

5.2 Control Group (G.CTL)

	Press SET/ENT key to select control group. (Refer to parameter map in section 3.) 
	This parameter establishes the set point for limit operation. This is the value set as the operating limit that will trigger the latching limit control relay. The parameter HI.LO sets if this is a high limit or a low limit.
	This parameter established the set point as a high or low limit value. If set as a high limit, the unit will consider the input beyond the set limit when $PV > SP$. If set as a low limit, the unit will consider the input beyond the set limit when $PV < SP$.
	This parameter determines the status of the latching relay (OUT1) when the unit is turned on. If R.MD is set as ON, the output condition will be a function the PV and SP as normal. If OFF, the output will enter over limit condition until reset. To set the condition of the relay in normal and over limit conditions, refer to parameter O.ACT below.
	This parameter sets the operation for the limit control latching relay (OUT1). In reverse (failsafe) operation, the control relay is energized during normal conditions. In forward operation, the control relay is energized during over limit conditions. The default setting is REV. See Fig 3 and 4 for a illustration showing reverse and forward operation.
	This parameter sets the hysteresis for the limit control. When returned within the limit range after being over the set limit, this is an additional amount below the limit that the PV must reach before the latching relay can be reset and the OVER LED turns off.
	This parameter sets a high limit on what the set points can be programmed or changed to. This value may reset if the type of input is changed, or if parameter IN.RH or IN.RL (IN. SH or IN.SL if input type is mV or V) is changed.
	This parameter sets a low limit on what the set points can be programmed or changed to. This value may reset if the type of input is changed, or if parameter IN.RH or IN.RL (IN. SH or IN.SL if input type is mV or V) are changed.
	Turning ON this parameter locks all other settings from being changed. This applies to the operation display functions, such as changing the set point, as well as setting group parameters. The default setting is OFF.
	This parameter establishes the password for the controller. This password must be entered at the PWD screen before accessing the control group (G.CTL) or it will not access the setting groups after the PWD prompt. The default setting is "0". See the parameter map in section 3 for the location of the PWD prompt in the group menus.



Be sure not to forget the password once it has been set. If the password is forgotten, contact technical support as listed on the back of this manual.

	This parameter sets the time units the controller uses for parameters with time components. This can be set to the format of HH.MM (hours.minutes) or MM.SS (minutes.seconds). Its default setting is HH.MM.
	This parameter resets most parameters to their factory settings. To reset the controller, set this parameter to ON. After reset, it will return to the OFF setting.



Most parameters will be reset to their default settings when the controller is initialized. Note the current settings before this is done so they can easily be restored after controller initialization.

5-2-1 Limit Control Features and Operations

5-2-1-1 Operation of Limit Functions when O.ACT = REV, HI.LO = HIGH, R.MD = OFF

The following illustration shows how each aspect of the limit control functions behave under over limit circumstances.

1. Power supplied to the controller. The OUT LED turns on.
2. The PV surpasses the SP. The OUT LED turns on. the OVER LED turns on. The latching limit control relay de-energizes. The time begins being recorded.
3. The PV falls below the limit and hysteresis levels. The OVER LED turns off. The time count stops.
4. The PV surpasses the SP. The OVER LED turns on. The time count resets and begins again.
5. The PV falls below the limit and hysteresis levels. the OVER LED turns off. The time count stops.

When the rest button is pressed for 3 seconds, and the PV is below the SP, the OUT LED will turn off, and the limit control relay will energize.

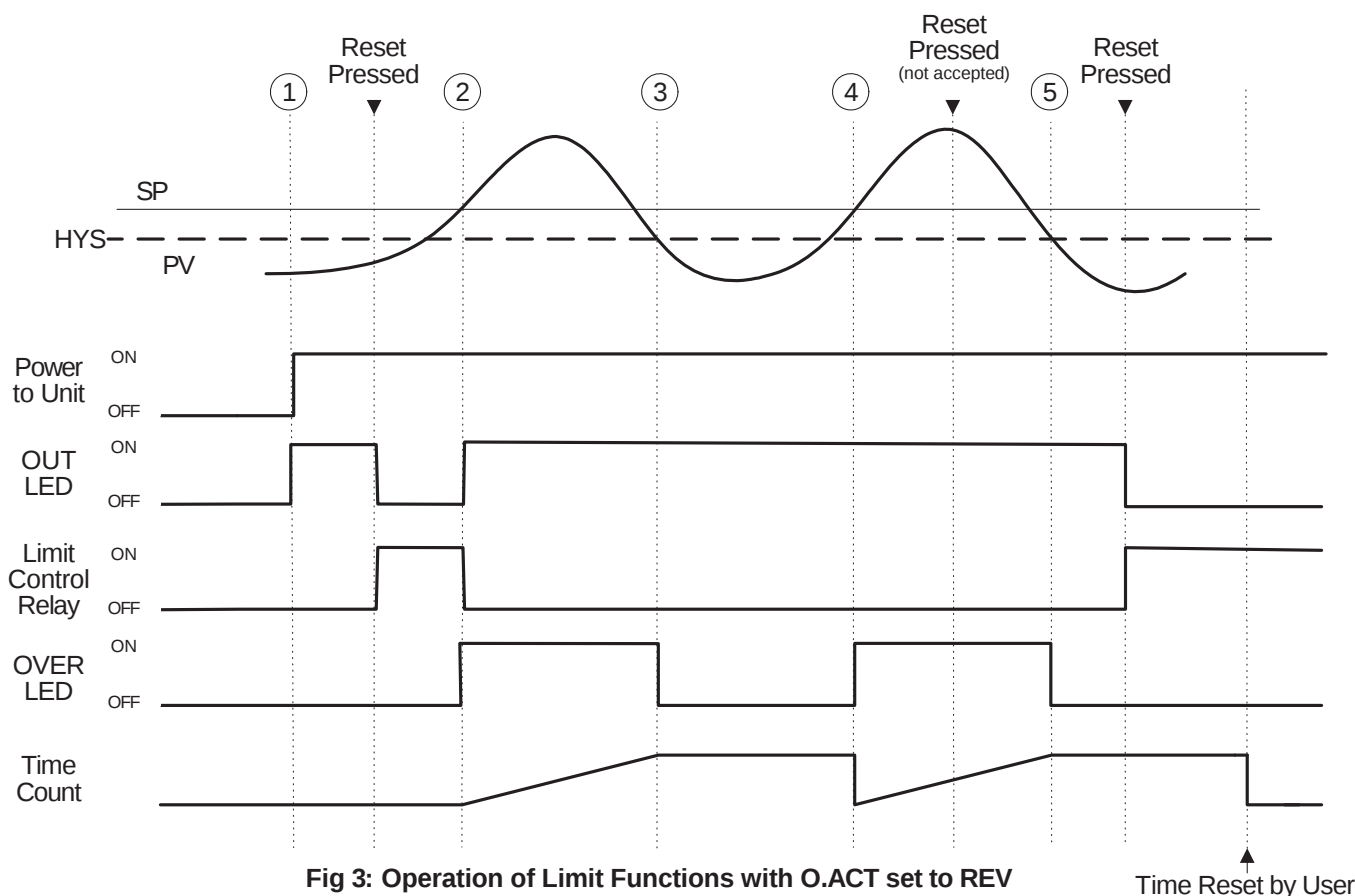


Fig 3: Operation of Limit Functions with O.ACT set to REV

Time Reset by User

5-2-1-2 Operation of Limit Functions when O.ACT = FWD, HI.LO = HIGH, R.MD = OFF

The following illustration shows how each aspect of the limit control functions behave under over limit circumstances when O.ACT is set to FWD operation.

1. Power supplied to the controller. The limit control relay energizes.
2. The PV surpasses the SP. The OUT LED turns off. the OVER LED turns on. The latching limit control relay energizes. The time begins being recorded.
3. The PV falls below the limit and hysteresis levels. The OVER LED turns off. The time count stops.
4. The PV surpasses the SP. The OVER LED turns on. The time count resets and begins again.
5. The PV falls below the limit and hysteresis levels. the OVER LED turns off. The time count stops.

When the rest button is pressed for 3 seconds, and the PV is below the SP, the OUT LED will turn on, and the limit control relay will turn off.

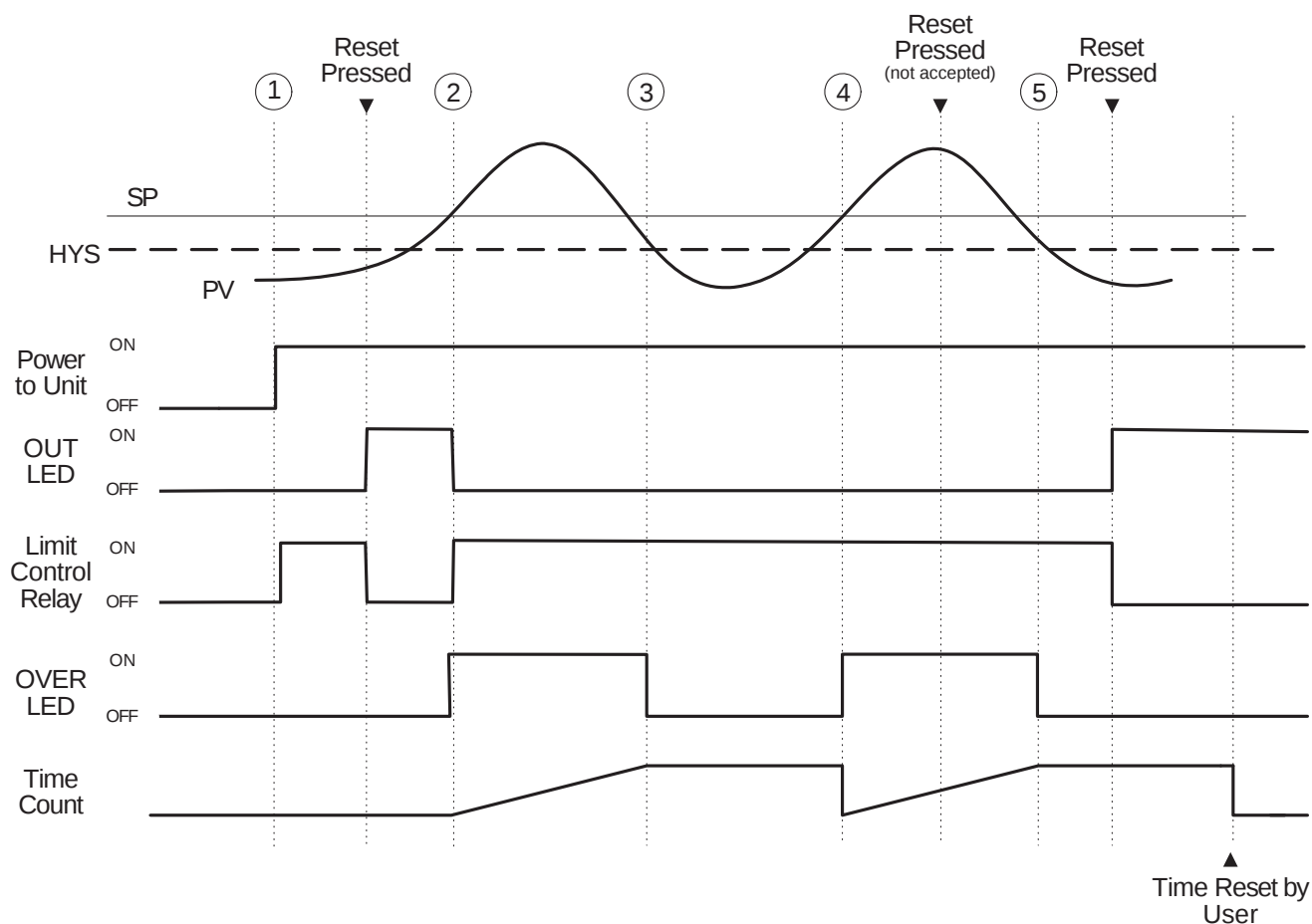


Fig 4: Operation of Limit Functions with O.ACT set to FWD

5-2-2 Limit Status Display and Reset Functions

The condition of the output can be seen by pressing the SET/ENT as shown in the Operation Flow Chart in section 4. The output status display refers to the condition of the limit control relay output.

The output display has two conditions, OFF and ON.

In the OFF condition:

Normally Closed (NC) Terminal: Closed

Normally Open (NO) Terminal: Open

In the ON condition:

Normally Closed (NC) Terminal: OPEN

Normally Open (NO) Terminal: CLOSED

To reset the limit control relay after the PV has gone over limit, it must be within the set point limit. Pressing the reset button for 3 seconds will return the limit control relay to OFF.

In the following illustration of output operation, HI.LO is set to HIGH, O.ACT set to REV, and R.MD set to OFF.

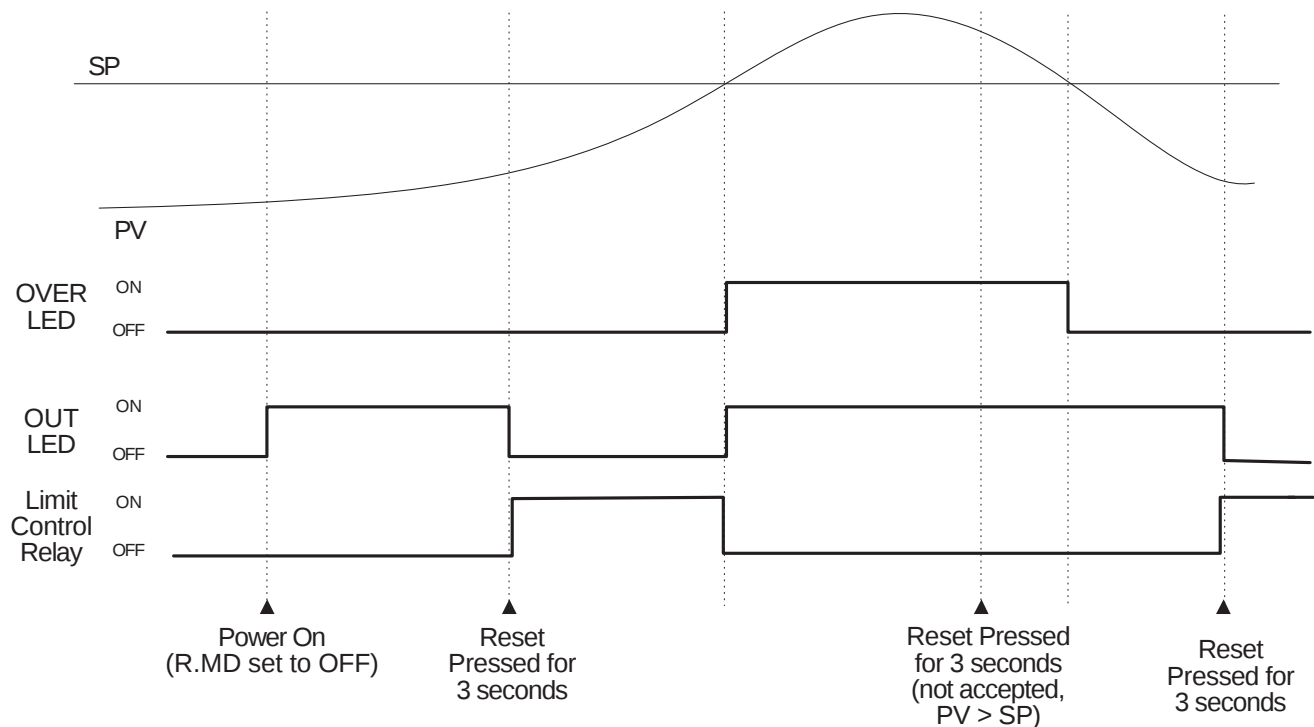


Fig 5: Example of Limit Control Relay Operation and Reset Function

5-2-3 Over Limit Timer

The time the PV has been over the SP limit is displayed in the operation display as shown in the Operation Flow Chart in section 4.

When the PV exceeds the SP value, the over limit timer begins operation. This will record the time that the PV is over the SP. If the PV returns to within the SP limit, the timer will stop. If following this the PV once again exceeds the SP, the timer will reset, and begin timing again.

The time passed cannot be reset while the PV is over the SP limit. If the PV is under the SP limit, the time count can be reset with the reset key.

The timer display range is:

0.0 - 999.9 min (HH.MM)

0.0 - 999.9 sec (MM.SS)

5-2-4 Maximum or Minimum PV Value Display

The maximum or minimum PV values are displayed in the operation display. Refer to the Operation Flow Chart in section 4.

If set for a high limit with HI.LO set to HIGH, the maximum PV value will be displayed. If set for a low limit with HI.LO set to LOW, the minimum PV value will be displayed. This value can be reset with the reset key while in the display screen.

Control Group Parameter Summary

Display	Parameter	Setting Range	Unit	Default	Remark
SP	Limit Set Point	AEU (0.0 to 100.0%)	AEU	AEU (0.0%)	
HI.LO	High or Low Limit Operation Selection	HI, LO	ABS	HI	
R.MD	Restart Relay Mode	ON, OFF	ABS	OFF	
O.ACT	Reverse and Forward Operation	REV, FWD	ABS	REV	
R.HYS	Hysteresis Value	GEU (0.0 to 10.0%)	GEU	GEU (0.5%)	
SPRH	Set Point Range High	AEU (0.0 to 100.0%)	AEU	AEU (100.0%)	
SPRL	Set Point Range Low	AEU (0.0 to 100.0%)	AEU	AEU (0.0%)	
LOCK	Parameter Lock	OFF, ON	ABS	OFF	
U.PWD	User Password	0 to 9999	ABS	0	
TMU	Time Unit	HH.MM, MM.SS	ABS	HH.MM	
INIT	Factory Initialization	OFF, ON	ABS	OFF	

5.3 Alarm Group (G.ALM)

	Press SET/ENT key to select alarm group. (Refer to parameter map in section 3.) 
	The parameter to set the type of alarm to be set for alarm 1. The types of alarms selectable are shown in Table 3: Alarm Selection.
	The parameter to set the alarm trigger point for the alarm set in ALT1. This parameter displays if a high, low, or high and low limit alarm was selected for ALT1.
	This establishes the high deviation range to trigger the alarm of deviation. This parameter displays if a deviation alarm was selected in ALT1.
	This establishes the low deviation range to trigger the alarm of deviation. This parameter displays if a deviation alarm was selected in ALT1.
	The parameter to set the dead band (Hysteresis) of alarm 1.
	The parameter to set the delay time before of alarm 1 is triggered.

Alarm Types and LED Display

SP 

- **S** indicates standby operation
- **F** for forward operation
- **r** for reverse (failsafe) operation
- Decimal point always displayed
- **H** indicates a high alarm
- **L** indicates a low alarm
- **a** for outside range of deviation band
- **I** for inside range of deviation band
- **A** indicates an absolute value alarm
- **d** indicates a deviation alarm

Alarm Output Settings:

- Forward: Relay energized in alarm condition
- Reverse: Failsafe operation. Relay energized during normal operating conditions

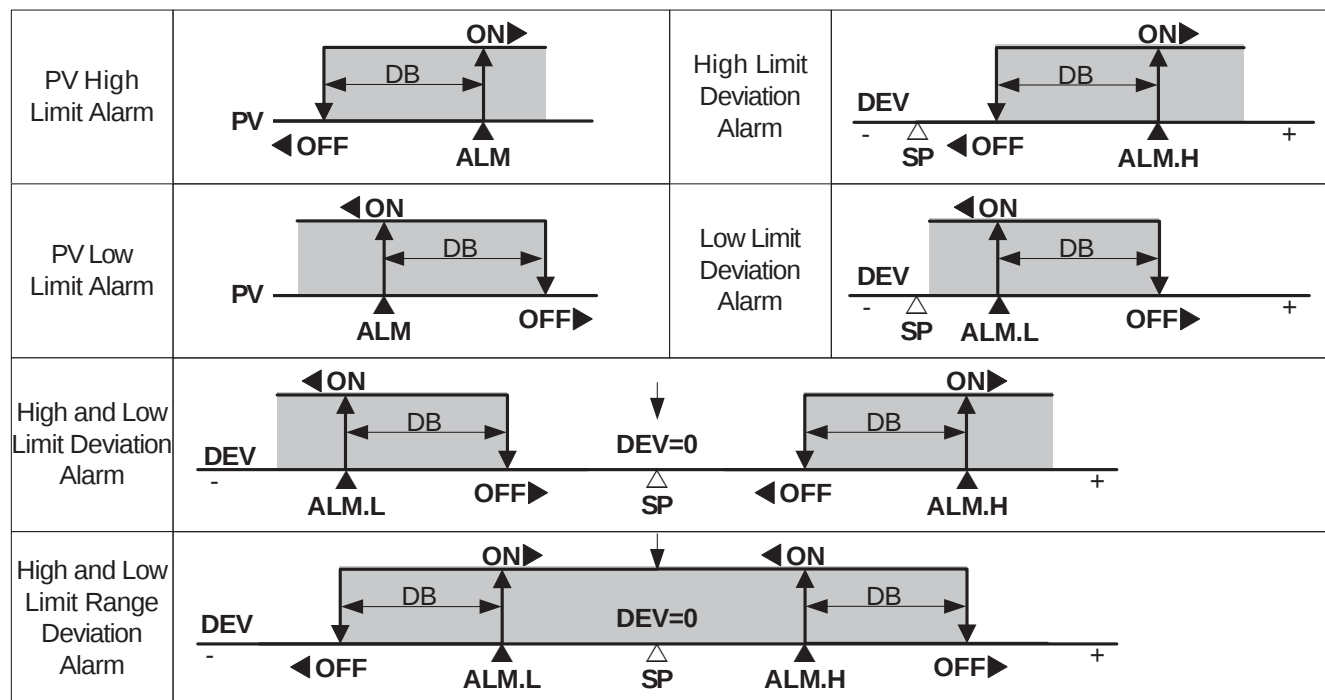
Standby Operation:

The alarm will not trigger if the alarm condition occurs during the following activities...

- during power-up
- the set point is changed
- the type of alarm is changed

Table 3: Alarm Selection

No.	Alarm Type	Operation		Standby		Display Data
		For	Rev	On	Off	
1	Absolute Value High Limit Alarm	✓		✓		AH.F
2	Absolute Value Low Limit Alarm	✓		✓		AL.F
3	High Limit Deviation Alarm	✓		✓		DH.F
4	Low Limit Deviation Alarm	✓		✓		DL.F
5	High Limit Deviation Alarm		✓	✓		DH.R
6	Low Limit Deviation Alarm		✓	✓		DL.R
7	High and Low Limit Deviation Alarm	✓		✓		DO.F
8	High and Low Limit Range Deviation Alarm	✓		✓		DI.F
9	Absolute Value High Limit Alarm		✓	✓		AH.R
10	Absolute Value Low Limit Alarm		✓	✓		AL.R
11	Absolute Value High Limit Alarm with Standby	✓			✓	AH.FS
12	Absolute Value Low Limit Alarm with Standby	✓			✓	AL.FS
13	High Limit Deviation Alarm with Standby	✓			✓	DH.FS
14	Low Limit Deviation Alarm with Standby	✓			✓	DL.FS
15	High Limit Deviation Alarm with Standby		✓		✓	DH.RS
16	Low Limit Deviation Alarm with Standby		✓		✓	DL.RS
17	High and Low Limit Deviation Alarm with Standby	✓			✓	DO.FS
18	High and Low Limit Range Deviation Alarmwith Standby	✓			✓	DI.FS
19	Absolute Value High Limit Alarm with Standby		✓		✓	AH.RS
20	Absolute Value Low Limit Alarm with Standby		✓		✓	AL.RS

**Fig 6: Alarm Operation**

Alarm Group Parameter Summary

Display	Parameter	Setting Range	Unit	Default	Remark
ALT1	Alarm Type 1	Refer to Table 3: Alarm Selection	ABS	AH.F	
AL-1	Set value of ALT1	AEU (-100.0 to 100.0%)	AEU	EU (100.0%)	Absolute Value Alarm
AL1.H	High Deviation Limit of Alarm 1	GEU (-100.0 to 100.0%)	GEU	EUS (0.0%)	Deviation Alarm
AL1.L	Low Deviation Limit of Alarm 1	GEU (-100.0 to 100.0%)	GEU	EUS (0.0%)	Deviation Alarm
A1DB	Alarm 1 DB	GEU (0.0 to 100.0%)	GEU	EUS (0.5%)	
A1DY	Delay Time of Alarm 1	0.00 to 99.59	MM.SS	0.00	

5.4 Retransmission Group (G.RET)

PV G-rEt

Press SET/ENT key to select retransmission group. (Refer to parameter map.)

PV rEt

This parameter sets the type of retransmission mode to use. The setting options are PV, SP, and LPS. See notes below for an explanation of the retransmission types. The default setting is PV.

PV rEtH

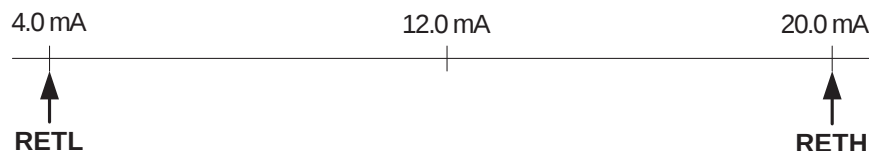
PV rEtL

These parameters are used to scale the retransmitting output. They set the high and low limits for the retransmission output scale, as shown below. The retransmitting outputs will transmit 4 mA at the low limit (RETL) and 20 mA at the high limit (RETH) values. These limits are used when the retransmission type is set to PV or SP.



PV and SP Type Retransmission Scale

PV type retransmits based on the input value, SP retransmits based on the set point value.



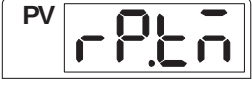
LPS Type Retransmission

LPS (Loop Power Supply) retransmitting outputs will transmit a 14-18 VDC @ 20 mA power supply output.

Retransmission Group Parameter Summary

Display	Parameter	Setting Range	Unit	Default	Remark
RET	Select Ret Type	PV, SP, LPS	ABS	PV	
RETH	Ret Scale High Limit	T/C, RTD: INRH to INRL mV, V: INSH to INSL RETH > RETL	AEU	INRH	
RETL	Ret Scale Low Limit		AEU	INRL	

5.5 Communication Group (G.COM)

	Press SET/ENT key to select communication group. (Refer to parameter map.) 
	The parameter to select the type of communication protocol to be used.
	The parameter to set the communication speed (baud rate). The baud rate can be set at 600 to 19200 bps (bytes per second). The default setting is for 9600 bps.
	The parameter to set communication parity. This can be set to NONE, EVEN, or ODD. The default setting is NONE.
	The parameter to set the communication stop bit. This can be set as 1 or 2. It is initially set as 1.
	The parameter to set the communication data length. This can be set to 7 or 8. The default setting is 8. This parameter is not displayed when the communication protocol (COM.P) is set for MODBUS ASCII or RTU.
	The parameter to set the communication address for the controller. This can be set as 1 to 99 pcs address. Its default setting is 1.
	The parameter to set communication response time. The RP.TM is the delay to return data to the upper level device after processing commands received from the upper level device. The setting RP.TM is based on the number of 10 ms intervals to delay (example: a setting of 2 will result in a 20 ms delay). If RP.TM is set to 0 it will immediately return a response once the command processing is complete.

Communication Group Parameter Summary

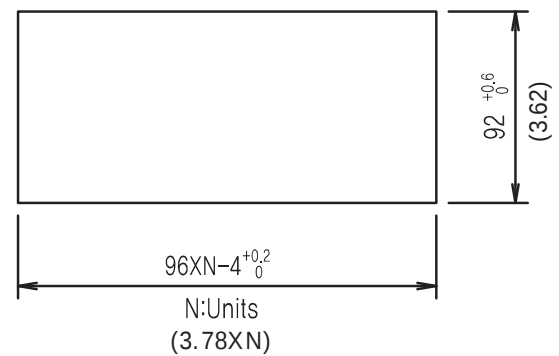
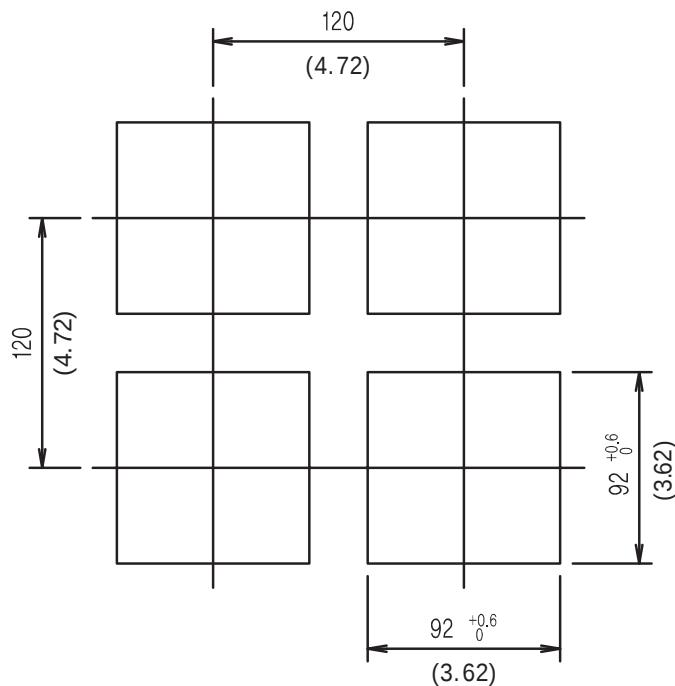
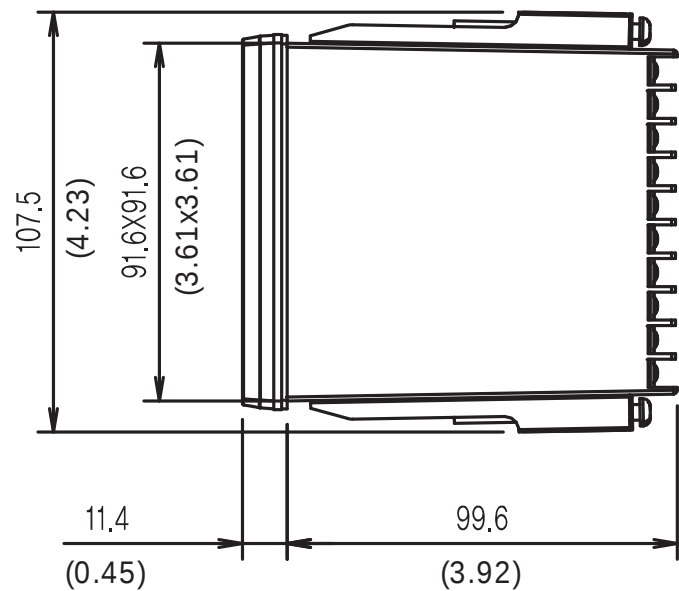
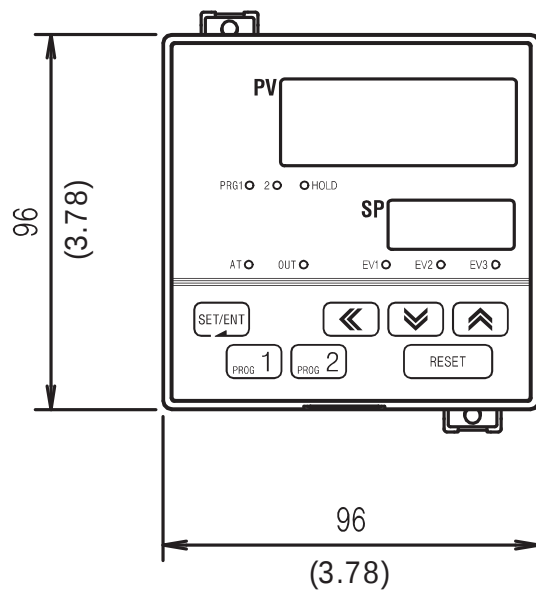
Display	Parameter	Setting Range	Unit	Default	Remark
COM.P	Communication Protocol	PCC0, PCC1, Modbus ASCII, Modbus RTU	ABS	PCC0	Option
BAUD	Baud Rate	600, 1200, 2400, 4800, 9600, 19200	ABS	9600	Option
PRTY	Parity	None, Even, Odd	ABS	None	Option
SBIT	Stop Bit	1, 2	ABS	1	Option
DLEN	Data Length	7, 8 (not used when set for MODBUS)	ABS	8	Option
ADDR	Address	1 to 99 (maximum of 31 connected at once)	ABS	1	Option
RP.TM	Response Time	0 to 10 (number of 10ms intervals)	ABS	0	Option

6. Error Display and Correction

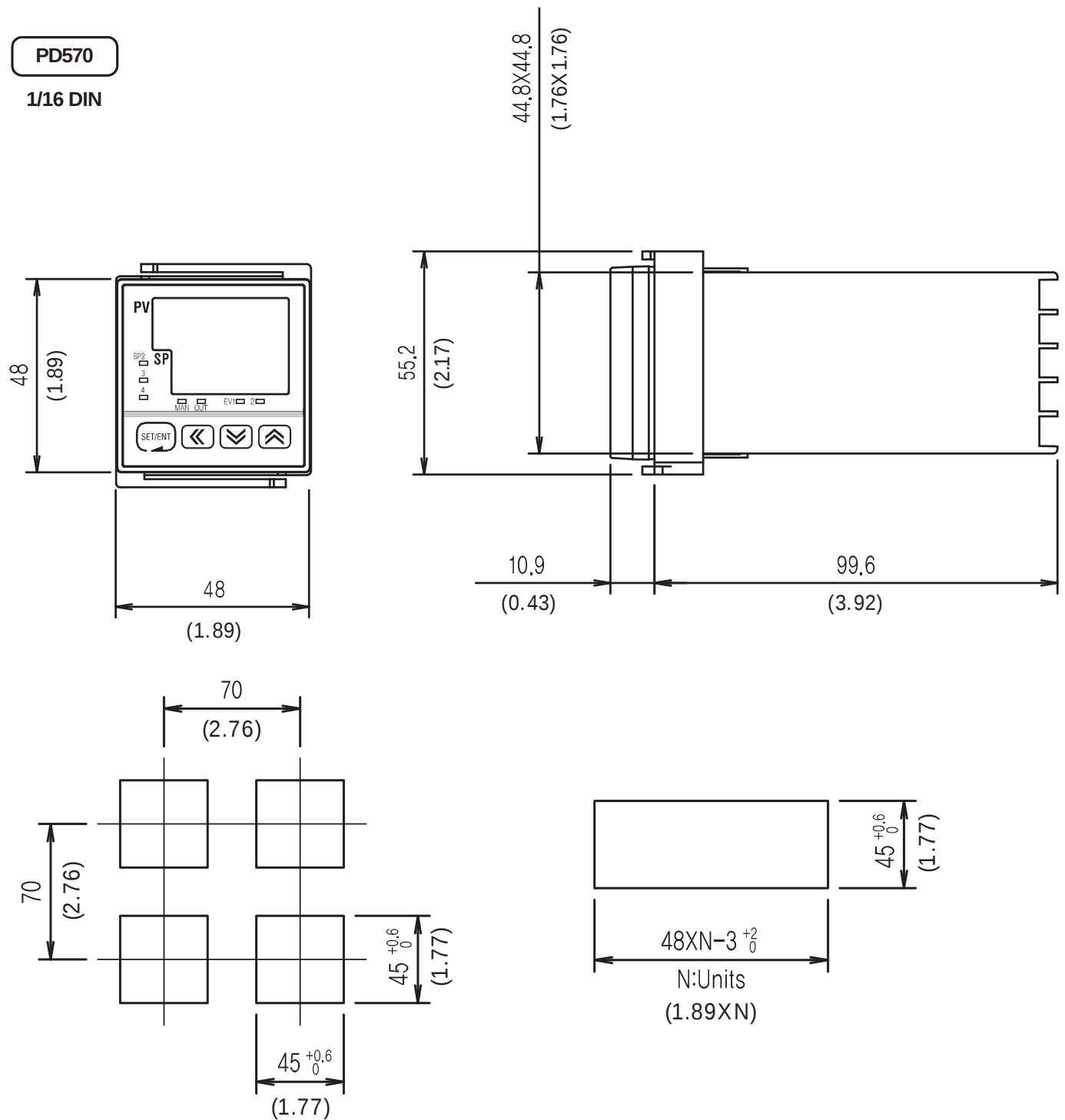
Error Message	Error Incident	Action Needed
E.SYS	EEPROM, Data Loss	Needs Repair
E.RJC	RJC Sensor Failure	Needs Repair
SP Decimal Flashing	Communication Failure	Check Comm Cable
S.OPN	Open Sensor Detected	Check Sensor

7. Installation

7.1 Dimensions and Panel Cutouts

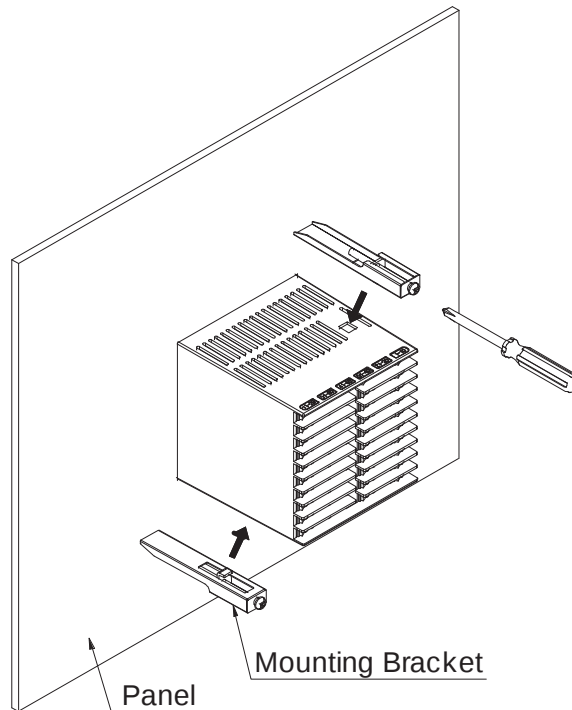
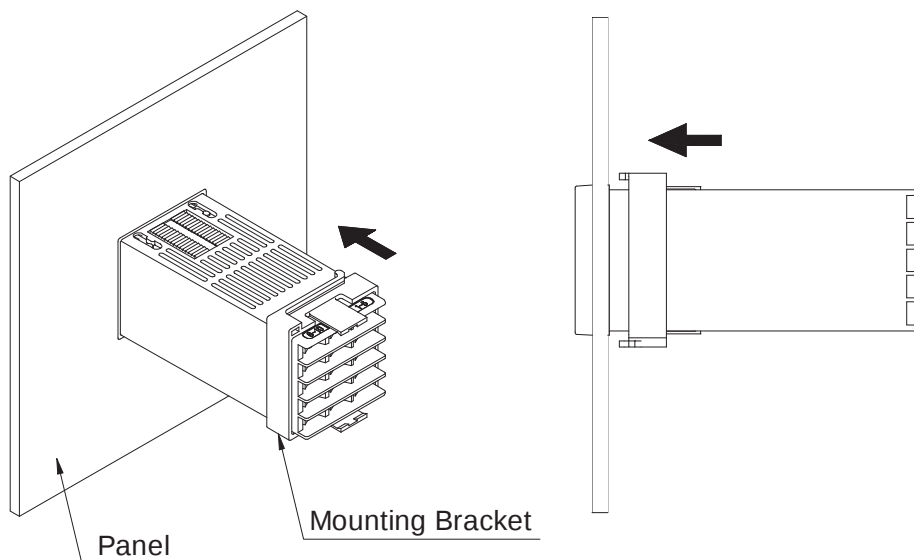
PD578**1/4 DIN**

Units: mm
(inch) - for reference only

PD570**1/16 DIN**

Units: mm
(inch) - for reference only

7.2 Panel Mounting

PD578**PD570**

Installation Steps

1. Cut the mounting panel. (Refer to 7.1 Dimensions and Panel Cutouts)
2. Insert the controller through the front of the panel rear terminals first.
3. On applicable models, attach the right and left mounting bracket and secure it to the panel.
4. On 1/16 DIN controller models, slide the mounting bracket onto the back of the controller as shown, and slide it forward on the controller until the bracket locks in place, and the controller is secure.



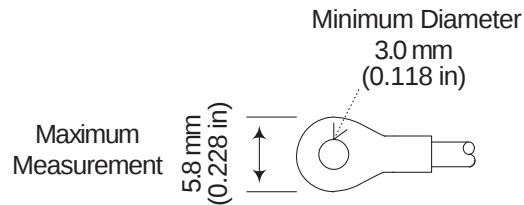
Do not excessively tighten the mounting bracket screws. Excessive tightening may lead to controller or panel damage.

7.3 Power Cable Specification

Make power connections using 0.9 to 2.0 mm² or 16 AWG vinyl insulated wire. (Voltage rating of 300 VAC)

7.4 Terminal Specification

Use M3.5 screw-compatible crimp on terminals with insulating sleeve as shown below.



Note: Inches for reference only.

Use copper conductors only if the terminal is for connection to copper wire only.



Always turn off the source circuit breaker and check to ensure the power is off to the controller through the use of a tester prior to working on the wiring terminals.

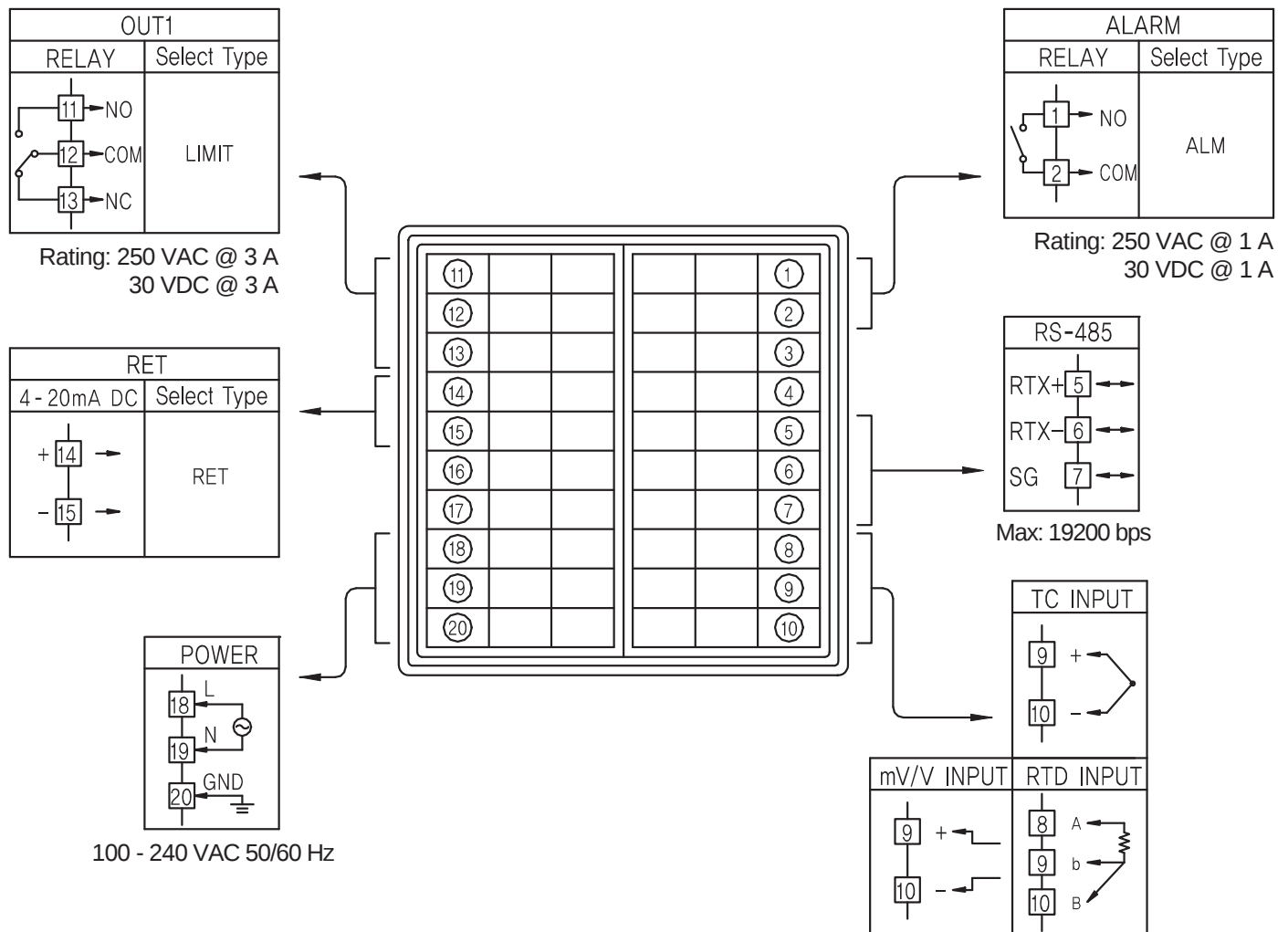
- Never touch the terminals in the rear panel when power is supplied to the controller.
- Be sure to turn off the electric power before wiring any terminals.



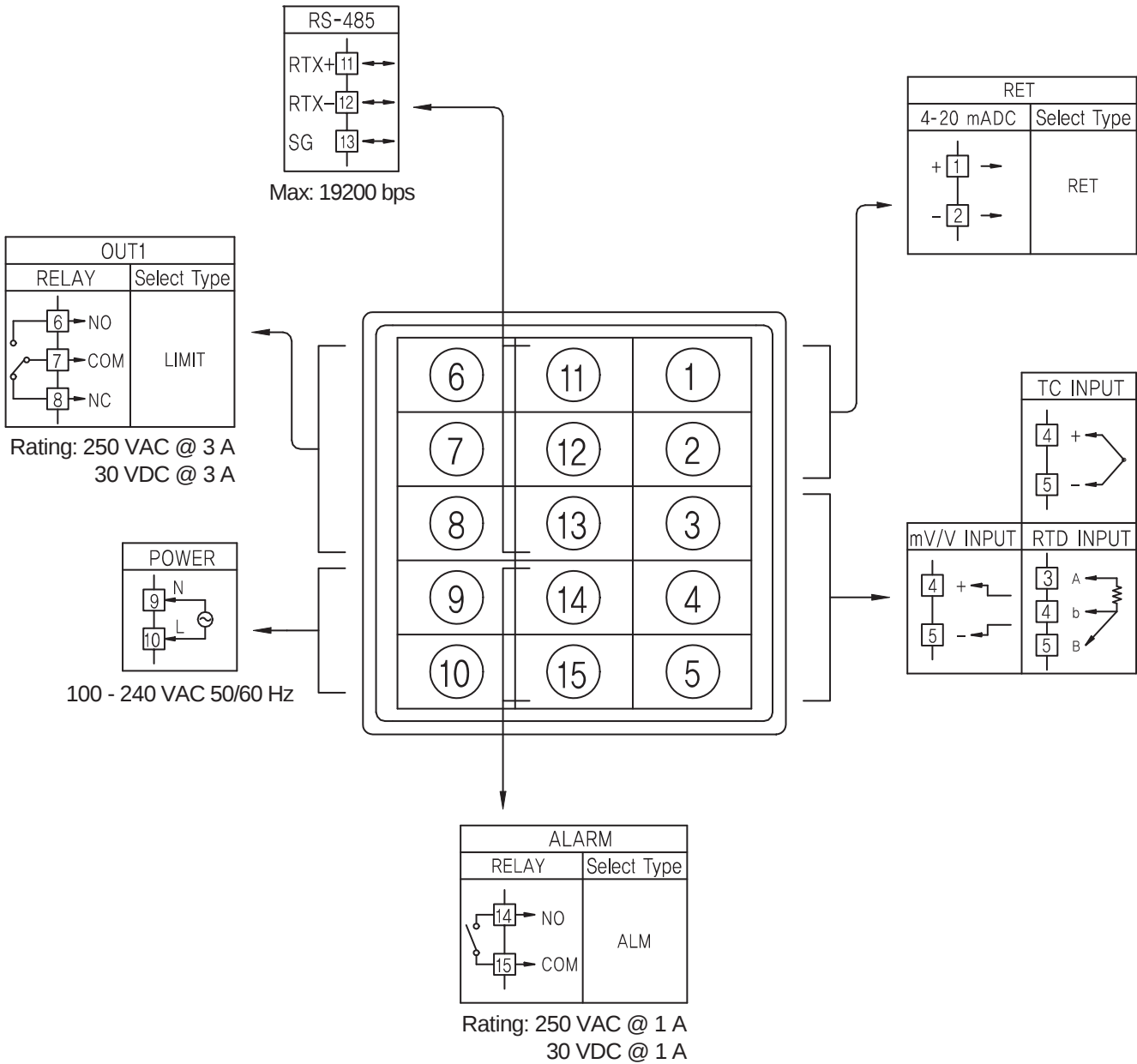
Bind the wires connected to the controller terminals neatly together in order to prevent electromagnetic interference.

7.5 Terminal Assignment, Connections, and Ratings

PD578

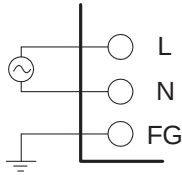


PD570



7.6 Grounding and Power Cable Connection

- Use a thick grounding cable of at least 2 mm² or 14 AWG and shorter than 20 m (approximately 22 ft) for class-3 grounding or better with a grounding resistance of less than 100 Ω .
- Be sure to ground from the grounding terminal to an independent grounding point. (1 point grounding)
- Use 0.9 to 2.0 mm² or 16 AWG vinyl insulated wire (Voltage rating 300VAC) or thicker for power cable connection.



Be sure to connect L (Hot), N (neutral), and GND (ground) as indicated. Failure to wire the power and ground as indicated could result in damage to the controller.



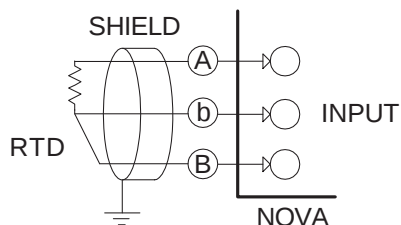
To prevent electric shock, be sure to turn off power to the Nova Controller and the source circuit breaker before wiring.



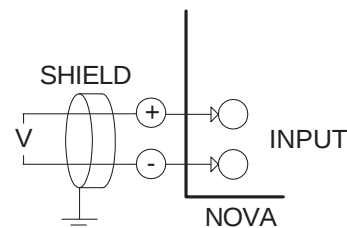
- Be sure to connect to correct polarities. Connecting to a wrong polarity may cause damage or malfunction.
- Use shielded wires and ground the shielding to an independent grounding point.
- Keep the input signal and output wiring as far as possible away from the power and ground circuit.
- Use a wire with low conductive resistance and no three-wire resistance differential.

7.7 Signal Input Connection

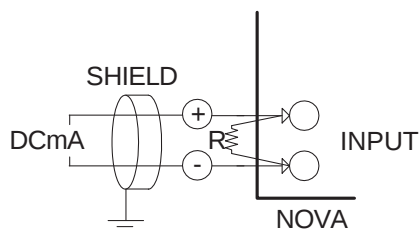
(1) RTD Input



(2) DC Voltage Input



(3) DC Current Input



To accept a 4-20 mA signal, select 0.4 to 2.0 VDC input and connect a 100 Ω resistor across the input terminals as shown.

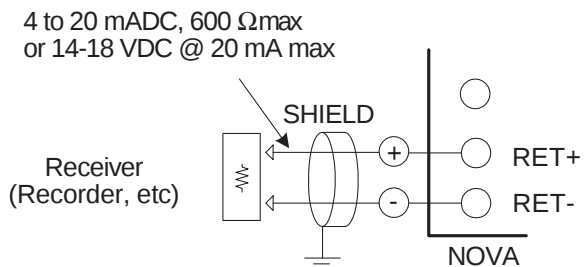
7.8 Retransmission Output Connection (RET)



To prevent electric shock, be sure to turn off power to the Nova Controller and the source circuit breaker before wiring.

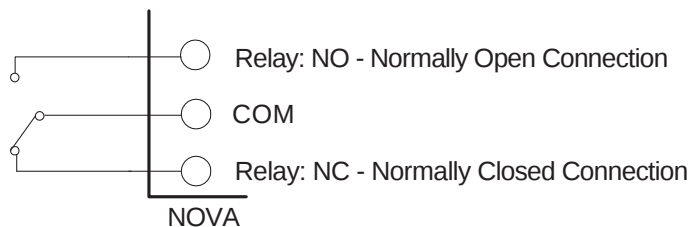


- Be sure to connect to correct polarities. Connecting to a wrong polarity may cause a controller malfunction.
- Use shielded wires for the wiring and connect independently to ground (1 point grounding).



To prevent electric shock, be sure to turn off power to the Nova Controller and the source circuit breaker before wiring.

7.9 Relay Output Connection (RELAY)



To prevent electric shock, be sure to turn off power to the Nova Controller and the source circuit breaker before wiring.

7.10 Use of an External Relay

Switching Inductive Loads

When using switching inductive loads, the use of RC networks (snubbers) for AC loads or diodes for DC loads is recommended to prevent disrupting the microprocessor's operation. The suppressors also prolong the life of the relay contacts. Suppression can be obtained with resistor-capacitor (RC) networks or diodes assembled by the user or purchased as complete assemblies.

For AC loads, choose R and C as follows:

R: 0.5 to 1 Ω for each volt across the contact

C: 0.5 to 1 μF for each amp through closed contacts

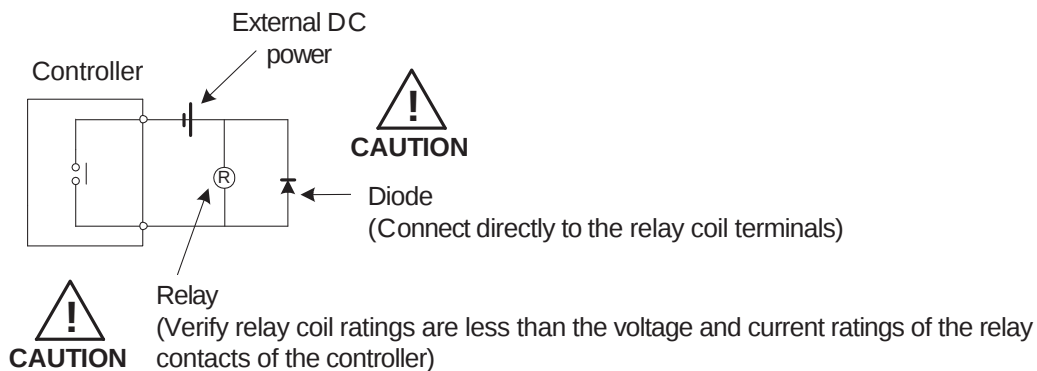
Notes:

1. Use capacitors rated for 250 VAC.
2. RC networks may affect load release time of solenoid loads. Check to confirm proper operation.
3. RC networks are available from Precision Digital and should be applied to each relay contact switching an inductive load. Part number: PDX6901.

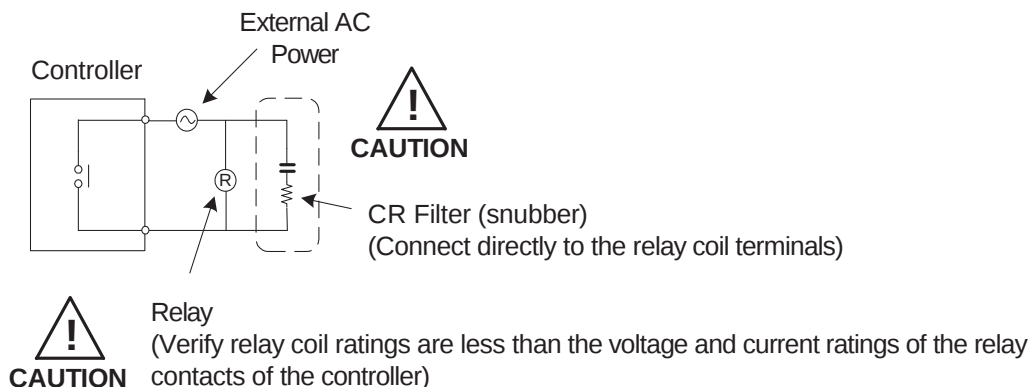


If the load inductance is over the controller specifications, the output may need a RC filter (snubber) or diode to properly handle frequent relay switching operations.

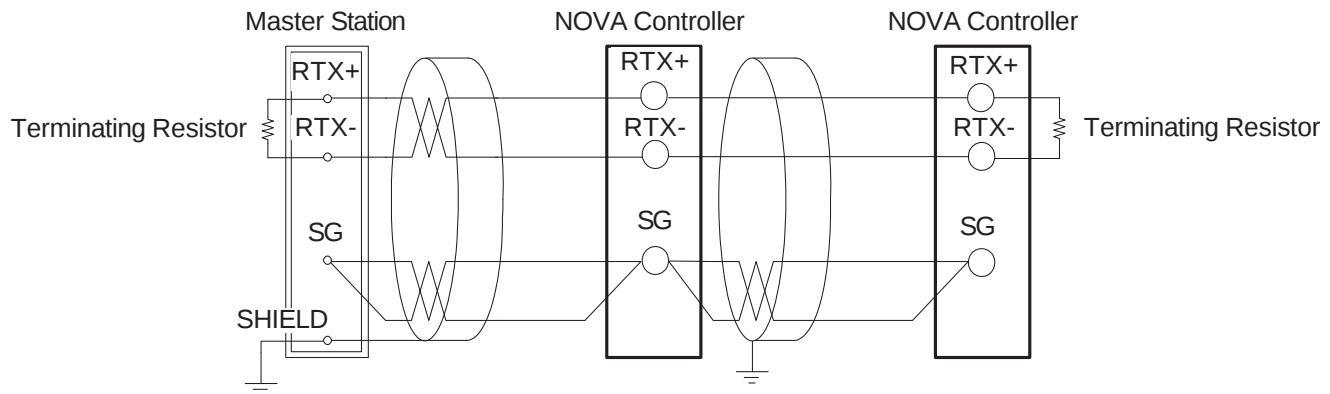
(1) DC External Relay



(2) AC External Relay



7.11 Communication Wiring (RS-485)



- Up to 31 slave controllers (Nova series controllers equipped with the RS-485 serial communication option) can be connected.
- Be sure to connect terminating resistors ($220\ \Omega$, $1/4\ W$) to slave and master controllers at communication channel ends as shown above.



To prevent electric shock, be sure to turn off power to the Nova Controller and the source circuit breaker before wiring.

Table of D-Registers:

The following data registers are used to direct the US1 and US2 commands or for Modbus communication.

NO.	PROCESS	FUNCTION	SET POINT	SIGNAL	ALARM	PID	IN/OUT
	0	100	200	300	400	500	600
0							
1	NPV		SP		ALT1		IN-T
2	NSP						INT-U
3							IN.RH
4							IN.RL
5							IN.DP
6					AL-1		IN.SH
7							IN.SL
8							IN.FL
9							BSL
10	NOWSTS						RSL
11			SPRH		A1DB		BSP1
12			SPRL				BSP2
13							BSP3
14	ALSTS		TMU				
15							BS0
16					A1DY		BS1
17							BS2
18							BS3
19							BS4
20							
21					AL1.H		
22							
23							
24							
25							
26					AL1.L		
27							
28							
29							
30							
31							
32							
33							
34							
35							
36							O.ACT
37		LOCK					
38	HI.VALUE						
39	LO.VALUE						
40	KEEP.TIME						
41		HI.LO					
42		R.MD					
43							

NO.	PROCESS	FUNCTION	SET POINT	SIGNAL	ALARM	PID	IN/OUT
	0	100	200	300	400	500	600
44							
45							HYS
46							
47							
48							
49							
50							
51							RET
52							RETH
53	U						RETL
54	s						
55	e						
56	r						
57							
58	A						
59	r						
60	e						
61	a						COM.P
62							BAUD
63							PRTY
64							SBIT
65							DLEN
66							ADDR
67							RP.TM
68							
69							
70							
71							
72							
73							
74							
75							
76							
77							
78							
79							
80							
81							
82							
83							
84							
85							
86							
87							

NO.	PROCESS	FUNCTION	SET POINT	SIGNAL	ALARM	PID	IN/OUT
	0	100	200	300	400	500	600
88							
89							
90							
91							
92							
93							
94							
95							
96							
97							
98							
99							



Read Only Location

Notes



Warranty and Return Information

Precision Digital warrants this product to be free from material defects and workmanship under normal use and service for three years.

Please contact Precision Digital Technical Support at (800) 610-5239 or e-mail at support@predig.com prior to any product return. When Technical Support determines a product should be returned, a Return Material Authorization (RMA) # which must be included on the return shipping label. Please also include the reason for return, date of purchase, contact name, and how to contact. Products returned for reasons other than repair may be subject to a restocking fee. Any returns under a warranty claim should be returned freight prepaid. Upon warranty confirmation Precision Digital will repair or replace and return the unit at no charge via UPS Ground. Other shipping is available upon request and at customer expense. All product returns should be shipped to:

Return Authorization # _____

Precision Digital, 233 South Street, Hopkinton, MA 01748 USA

Attention: Technical Support

Precision Digital Technical Support is trained and eager to serve you. We have found most start-up problems to be the result of incorrect signal connections and/or programming. Most often Precision Digital Technical Support can quickly correct these issues over the telephone.

